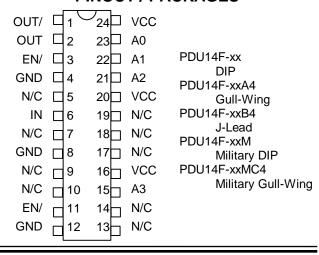
# 4-BIT PROGRAMMABLE **DELAY LINE** SERIES PDU14F)



#### **FEATURES**

- Digitally programmable in 16 delay steps
- Monotonic delay-versus-address variation
- Two separate outputs: inverting & non-inverting
- Precise and stable delays
- Input & outputs fully TTL interfaced & buffered
- 10 T<sup>2</sup>L fan-out capability
- Fits standard 24-pin DIP socket
- Auto-insertable

## **PINOUT / PACKAGES**



#### **FUNCTIONAL DESCRIPTION**

The PDU14F-series device is a 4-bit digitally programmable delay line. The delay, TD<sub>A</sub>, from the input pin (IN) to the output pins (OUT, OUT/) depends on the address code (A3-A0) according to the following formula:

$$TD_A = TD_0 + T_{INC} * A$$

where A is the address code, Tinc is the incremental delay of the device, and TD<sub>0</sub> is the inherent delay of the device. The incremental delay is specified by the dash number of the device and can range from 0.5ns through 100ns, inclusively. The enable pins (EN/) are held LOW during

## PIN DESCRIPTIONS

IN Delay Line Input OUT Non-inverted Output OUT/ Inverted Output A0-A3 Address Bits EN/ **Output Enable** VCC +5 Volts GND Ground

normal operation. These pins must always be in the same state and may be tied together externally. When these signals are brought HIGH, OUT and OUT/ are forced into LOW and HIGH states, respectively. The address is not latched and must remain asserted during normal operation.

## **SERIES SPECIFICATIONS**

- Total programmed delay tolerance: 5% or 1ns, whichever is greater\*
- Inherent delay (TD<sub>0</sub>): 9ns typical (OUT)\* 8ns typical (OUT/)
- Setup time and propagation delay:

Address to input setup (T<sub>AIS</sub>):

Disable to output delay (T<sub>DISO</sub>): 6ns typ. (OUT)

Operating temperature: 0° to 70° C

Temperature coefficient: 100PPM/°C (excludes TD<sub>0</sub>)

Supply voltage V<sub>CC</sub>: 5VDC ± 5% Supply current: I<sub>CCH</sub> = 74ma  $I_{CCL} = 30 ma$ 

Minimum pulse width: 10% of total delay

\*For military-grade devices, the delay tolerance is 5% or 1.5ns, and

#### DASH NUMBER SPECIFICATIONS

Part Number	Delay Per Step (ns)	Total Delay Change (ns)	
PDU14F5	$0.5\pm0.3$	$7.5 \pm 1.0$	
PDU14F-0.78	$0.78 \pm 0.4$	11.7 ± 1.0	
PDU14F-1	$1\pm0.5$	$15 \pm 1.0$	
PDU14F-2	$2\pm0.5$	$30 \pm 1.5$	
PDU14F-4	4 ± 1.0	$60 \pm 3.0$	
PDU14F-5	5 ± 1.0	$75\pm3.8$	
PDU14F-10	$10 \pm 1.5$	$150 \pm 7.5$	
PDU14F-15	$15\pm1.5$	$225 \pm 11.3$	
PDU14F-20	$20\pm2.0$	$300 \pm 15.0$	
PDU14F-30	$30 \pm 3.0$	$450 \pm 22.5$	
PDU14F-40	$40\pm4.0$	$600 \pm 30.0$	
PDU14F-50	$50 \pm 5.0$	$750 \pm 37.5$	
PDU14F-100	$100 \pm 10.0$	$1,500 \pm 75.0$	

NOTE: Any dash number between .5 and 100 not shown is also available.

the inherent delay is typically 12.5ns

©2013 Data Delay Devices

## APPLICATION NOTES

## **ADDRESS UPDATE**

The PDU14F is a memory device. As such, special precautions must be taken when changing the delay address in order to prevent spurious output signals. The timing restrictions are shown in Figure 1.

After the last signal edge to be delayed has appeared on the OUT pin, a minimum time, T<sub>OAX</sub>, is required before the address lines can change. This time is given by the following relation:

$$T_{OAX} = max \{ (A_i - A_{i-1}) * T_{INC}, 0 \}$$

where  $A_{i-1}$  and  $A_i$  are the old and new address codes, respectively. Violation of this constraint may, depending on the history of the input signal, cause spurious signals to appear on the OUT pin. The possibility of spurious signals persists until the required  $T_{OAX}$  has elapsed.

A similar situation occurs when using the EN/ signal to disable the output while IN is active. In this case, the unit must be held in the disabled state until the device is able to "clear" itself. This is achieved by holding the EN/ signal high and the IN signal low for a time given by:

$$T_{DISH} = A_i * T_{INC}$$

Violation of this constraint may, depending on the history of the input signal, cause spurious signals to appear on the OUT pin. The possibility of

spurious signals persists until the required  $\mathsf{T}_{\mathsf{DISH}}$  has elapsed.

#### INPUT RESTRICTIONS

There are three types of restrictions on input pulse width and period listed in the AC Characteristics table. The recommended conditions are those for which the delay tolerance specifications and monotonicity are guaranteed. The suggested conditions are those for which signals will propagate through the unit without significant distortion. The absolute conditions are those for which the unit will produce some type of output for a given input.

When operating the unit between the recommended and absolute conditions, the delays may deviate from their values at low frequency. However, these deviations will remain constant from pulse to pulse if the input pulse width and period remain fixed. In other words, the delay of the unit exhibits frequency and pulse width dependence when operated beyond the recommended conditions. Please consult the technical staff at Data Delay Devices if your application has specific high-frequency requirements.

Please note that the increment tolerances listed represent a design goal. Although most delay increments will fall within tolerance, they are not guaranteed throughout the address range of the unit. Monotonicity is, however, guaranteed over all addresses.

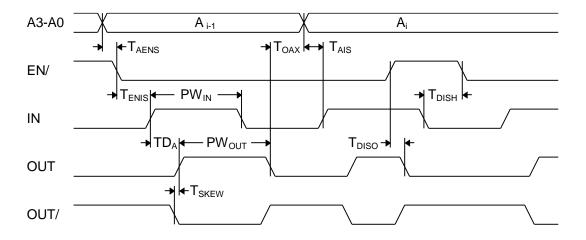


Figure 1: Timing Diagram

## **DEVICE SPECIFICATIONS**

**TABLE 1: AC CHARACTERISTICS** 

PARAMETER		SYMBOL	MIN	TYP	UNITS
Total Programmable Delay		$TD_T$		15	T <sub>INC</sub>
Inherent Delay		TD <sub>0</sub>		9.0	ns
Output Skew		T <sub>SKEW</sub>		1.5	ns
Disable to Output Low Delay		T <sub>DISO</sub>		6.0	ns
Address to Enable Setup Time		TAENS	2.0		ns
Address to Input Setup Time		T <sub>AIS</sub>	5.0		ns
Enable to Input Setup Time		TENIS	2.5		ns
Output to Address Change		Toax	See Text		
Disable Hold Time		T <sub>DISH</sub>	See Text		
Input Period	Absolute	PERIN	20		% of TD <sub>T</sub>
	Suggested	PERIN	40		% of TD <sub>T</sub>
	Recommended	PERIN	200		% of TD <sub>T</sub>
Input Pulse Width	Absolute	PW <sub>IN</sub>	10		% of TD <sub>T</sub>
	Suggested	PW <sub>IN</sub>	20		% of TD⊤
	Recommended	PWin	100		% of TD <sub>T</sub>

**TABLE 2: ABSOLUTE MAXIMUM RATINGS** 

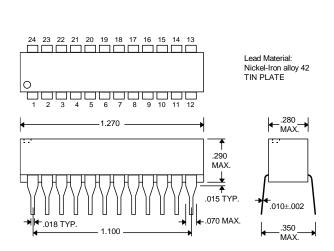
PARAMETER	SYMBOL	MIN	MAX	UNITS	NOTES
DC Supply Voltage	Vcc	-0.3	7.0	V	
Input Pin Voltage	VIN	-0.3	V <sub>DD</sub> +0.3	V	
Storage Temperature	T <sub>STRG</sub>	-55	150	С	
Lead Temperature	T <sub>LEAD</sub>		300	С	10 sec

**TABLE 3: DC ELECTRICAL CHARACTERISTICS** 

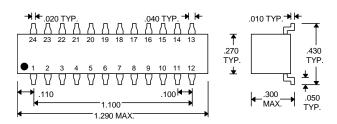
(0C to 70C, 4.75V to 5.25V)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
High Level Output Voltage	Vон	2.5	3.4		V	Vcc = MIN, IoH = MAX
						$V_{IH} = MIN, V_{IL} = MAX$
Low Level Output Voltage	Vol		0.35	0.5	V	$V_{CC} = MIN, I_{OL} = MAX$
						$V_{IH} = MIN, V_{IL} = MAX$
High Level Output Current	I <sub>OH</sub>			-1.0	mA	
Low Level Output Current	loL			20.0	mA	
High Level Input Voltage	ViH	2.0			V	
Low Level Input Voltage	V <sub>IL</sub>			8.0	V	
Input Clamp Voltage	Vıĸ			-1.2	V	$V_{CC} = MIN, I_I = I_{IK}$
Input Current at Maximum	Іінн			0.1	mA	$V_{CC} = MAX, V_I = 7.0V$
Input Voltage						
High Level Input Current	Iн			20	μΑ	$V_{CC} = MAX$ , $V_I = 2.7V$
Low Level Input Current	I₁∟			-0.6	mA	$V_{CC} = MAX, V_I = 0.5V$
Short-circuit Output Current	los	-60		-150	mA	$V_{CC} = MAX$
Output High Fan-out	_			25	Unit	
Output Low Fan-out				12.5	Load	

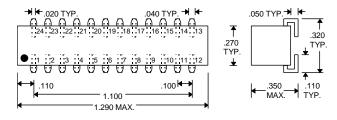
## PACKAGE DIMENSIONS



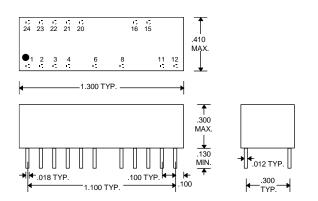
Commercial DIP (PDU14F-xx)



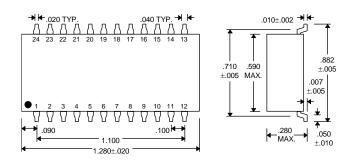
Commercial Gull-Wing (PDU14F-xxA4)



Commercial J-Lead (PDU14F-xxB4)



Military DIP (PDU14F-xxM)



Military Gull-Wing (PDU14F-xxMC4)

## **DELAY LINE AUTOMATED TESTING**

## **TEST CONDITIONS**

INPUT: OUTPUT:

**Ambient Temperature:**  $25^{\circ}\text{C} \pm 3^{\circ}\text{C}$  **Load:** 1 FAST-TTL Gate

**Supply Voltage (Vcc):**  $5.0V \pm 0.1V$  **C**<sub>load</sub>:  $5pf \pm 10\%$ 

**Input Pulse:** High =  $3.0V \pm 0.1V$  **Threshold:** 1.5V (Rising & Falling)

Low =  $0.0V \pm 0.1V$ 

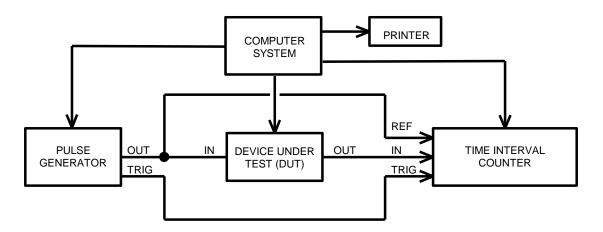
**Source Impedance:**  $50\Omega$  Max.

Rise/Fall Time: 3.0 ns Max. (measured

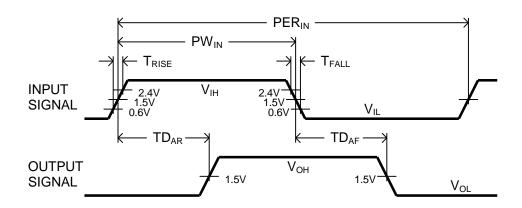
between 0.6V and 2.4V)

Pulse Width: $PW_{IN} = 1.5 \text{ x Total Delay}$ Period: $PER_{IN} = 4.5 \text{ x Total Delay}$ 

NOTE: The above conditions are for test only and do not in any way restrict the operation of the device.



**Test Setup** 



**Timing Diagram For Testing**